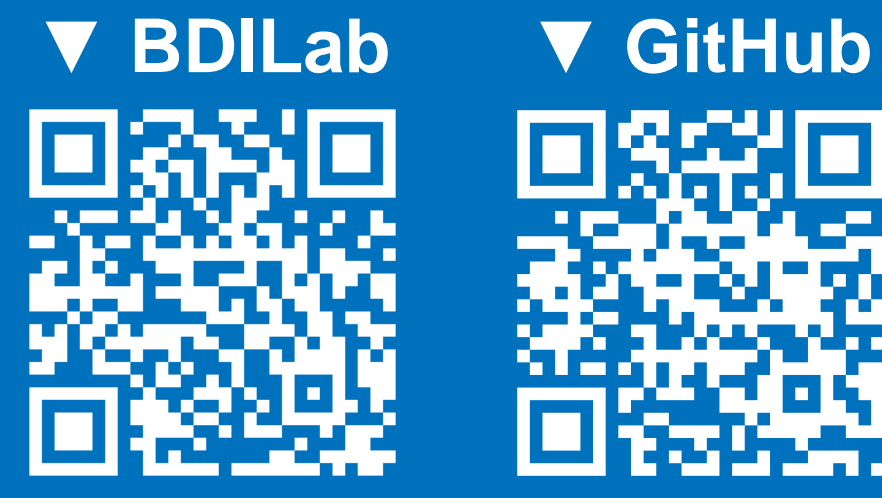
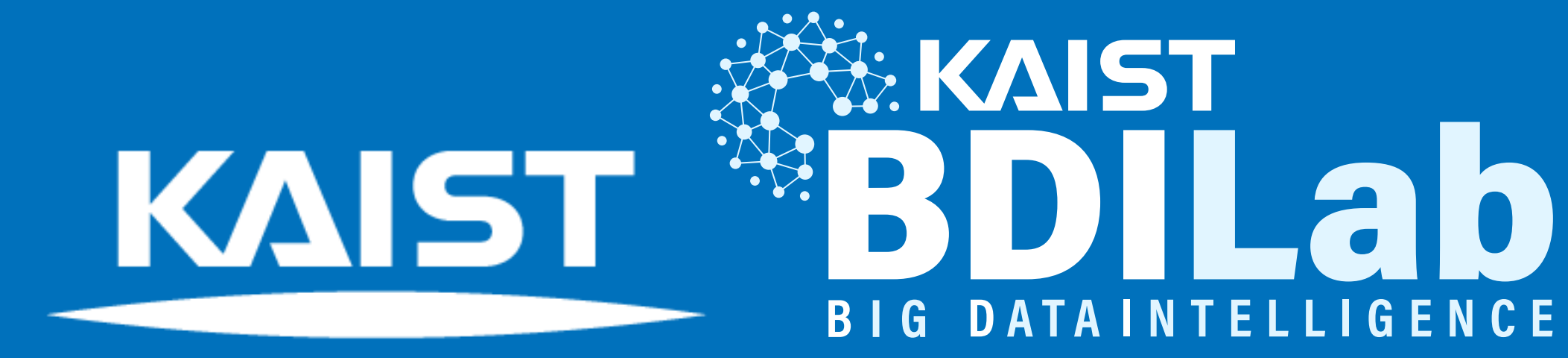


PAC-Bayesian Generalization Bounds for Knowledge Graph Representation Learning



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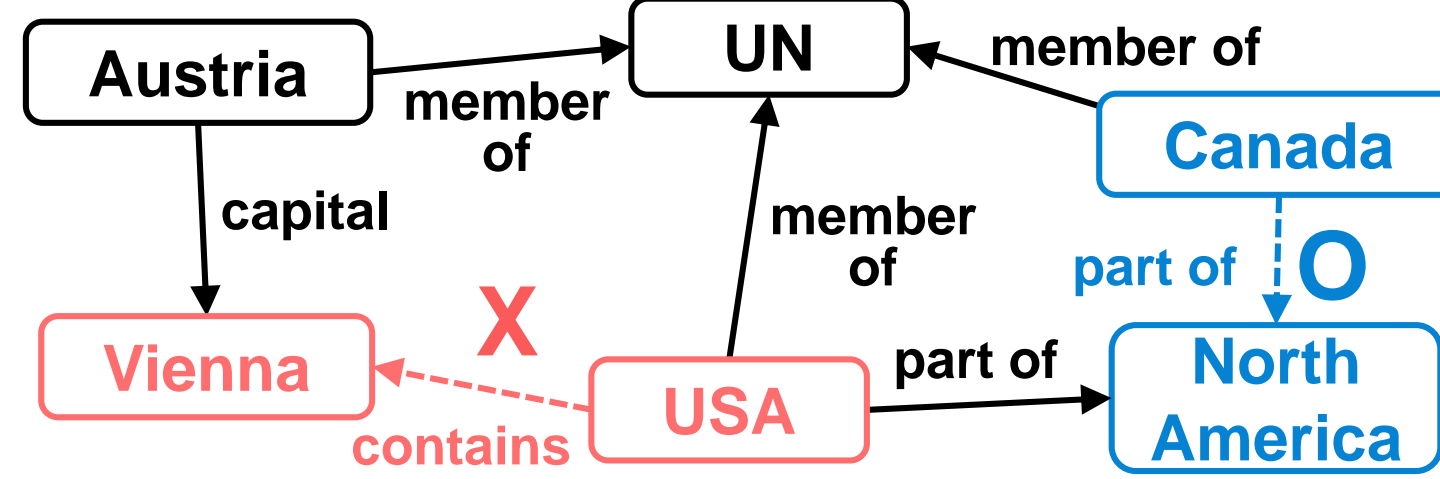
Main Contributions

- ReED framework** representing at least 15 different KGRL methods
 - RAMP encoder** in ReED is a comprehensive neural encoder for KGRL that can express models such as CompGCN and R-GCN
 - Formulate two types of **triplet classification decoders** in ReED
- Prove the **generalization bounds** for the ReED framework
 - The first study about **PAC-Bayesian generalization bounds** for KGRL
 - Analyze theoretical findings** from a practical model design perspective
- Empirically show** that the critical factors in generalization bounds can **explain actual generalization errors** on three real-world KGs

Knowledge Graphs (KGs)

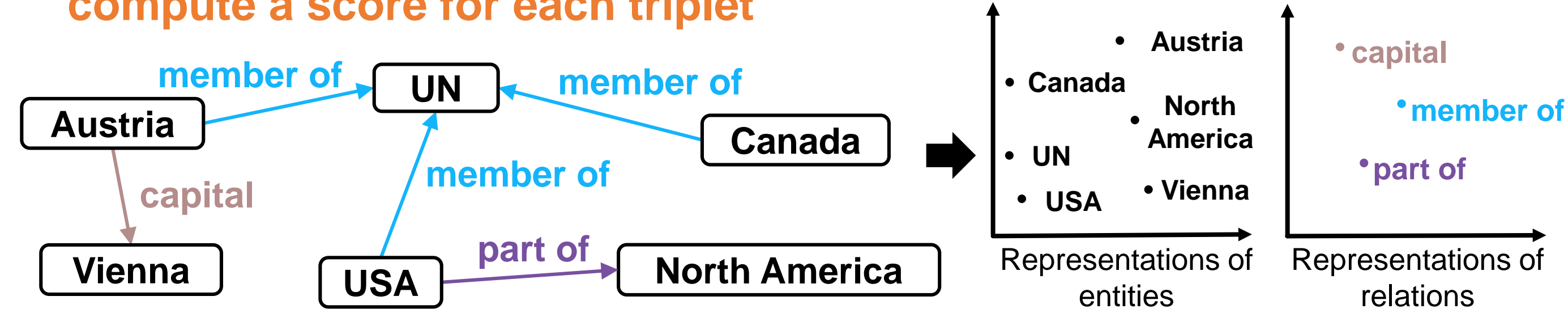
Triplet classification on a KG

- A model determines whether a given triplet is **plausible or not**



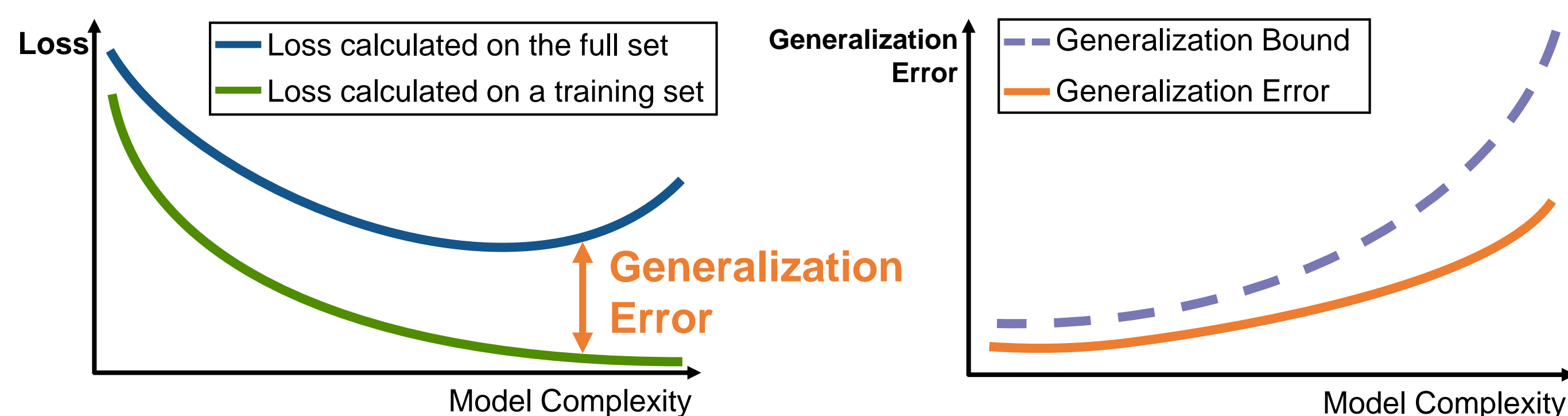
Knowledge Graph Representation Learning (KGRL)

- By **learning representations** of the entities and relations, KGRL methods **compute a score for each triplet**



Generalization Bound

- Generalization Error**
 - Difference** between the losses computed on the **full set** and a **training set**
- Generalization Bound**
 - Theoretical upper bound** of the generalization error



Transductive PAC-Bayesian Generalization Bounds

- Probably Approximately Correct (PAC) Theory**
 - Fundamental tools for analyzing the **generalization bounds**
- PAC-Bayesian Generalization Bounds**
 - Based on the difference between the **prior and posterior distributions**
- Transductive PAC-Bayesian Generalization Bounds**
 - Training triplets are **sampled without replacement** from the **finite** full set

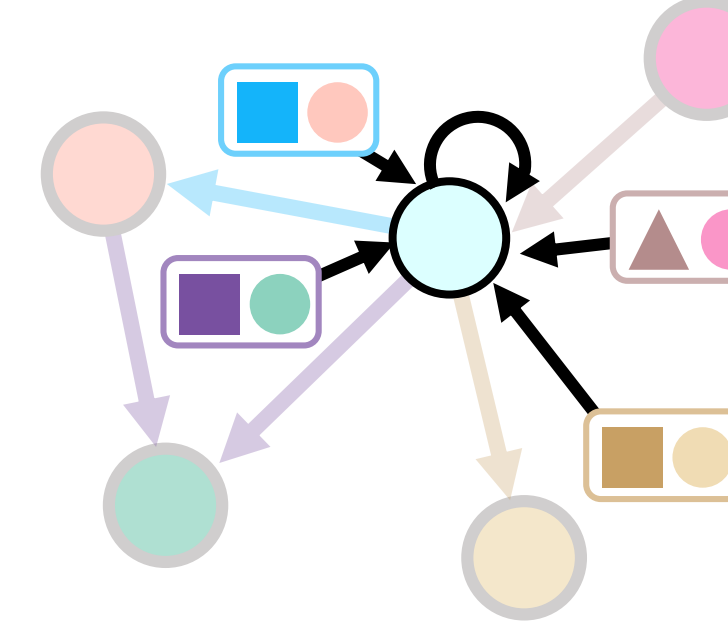
Relation-aware Encoder-Decoder Framework (ReED)

- Relation-Aware Message Passing Encoder (RAMP Encoder)**
 - Aggregating representations** of the neighboring entities and relations

$$M_r^{(l)}[v, :] = [H^{(l-1)}[v, :] \quad R^{(l-1)}[r, :]] \quad v \in \mathcal{V}, r \in \mathcal{R}$$

$$H^{(l)} = \phi \left(H^{(l-1)} W_0^{(l)} + \rho \left(\sum_{r \in \mathcal{R}} s_r^{(l)} \psi \left(M_r^{(l)} \left[W_r^{(l)} \right] \right) \right) \right)$$

$$R^{(l)} = R^{(l-1)} U_0^{(l)}$$



- Triplet Classification Decoder**
 - Using the entity and relation representations, **compute scores of triplets**
- Translational Distance Decoder (TD decoder)**
 - Distance** between h and t after a relation-specific translation is carried out

$$f_w(h, r, t)[j] = - \left\| H^{(L)}[h, :] \bar{W}_r^{(j)} + R^{(L)}[r, :] \bar{U}_r^{(j)} - H^{(L)}[t, :] V_r^{(j)} \right\|_2$$

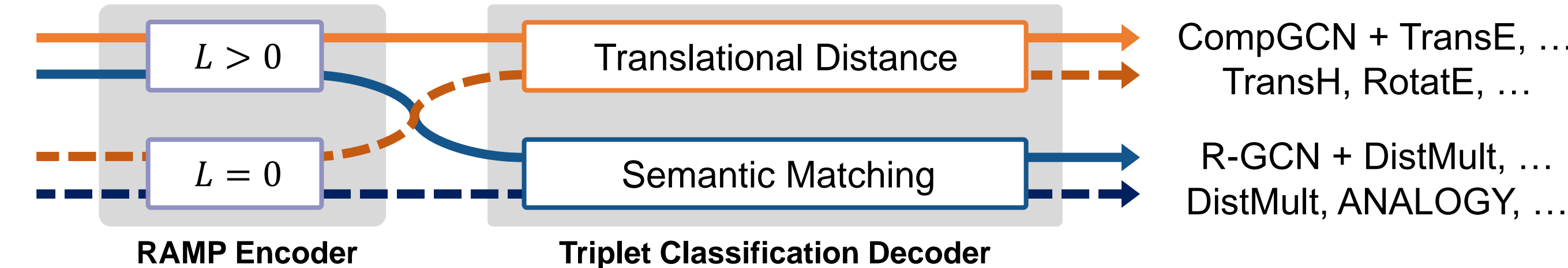
- Semantic Matching Decoder (SM decoder)**

- Similarity** between the individual components of the triplet

$$f_w(h, r, t)[j] = H^{(L)}[h, :] \bar{U}_r^{(j)} (H^{(L)}[t, :])^T$$

Instantiations of ReED

- ReED can express various KGRL methods using **different combinations** of the RAMP encoder and the triplet classification decoder



Empirical and Expected Losses of a Triplet Classifier

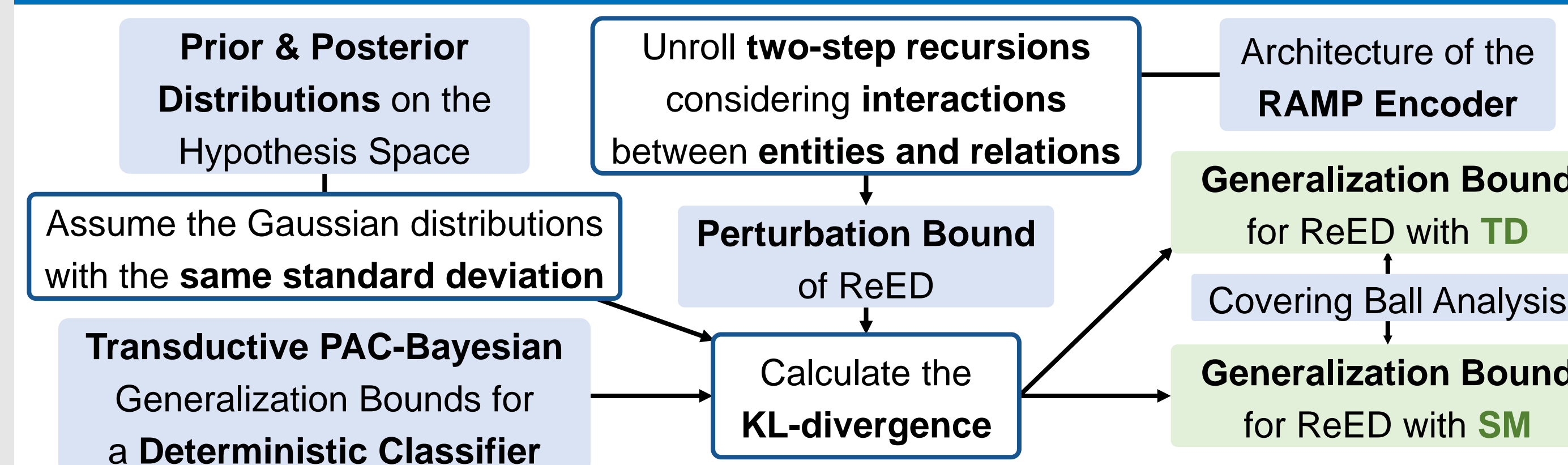
- Empirical Loss** of Triplet Classifier f_w : Measured on a **training triplet set** $\hat{\mathcal{E}}$

$$\mathcal{L}_{\gamma, \hat{\mathcal{E}}}(f_w) = \frac{1}{|\hat{\mathcal{E}}|} \sum_{(h, r, t) \in \hat{\mathcal{E}}} \mathbf{1}[f_w(h, r, t)[y_{hrt}] \leq \gamma + f_w(h, r, t)[1 - y_{hrt}]]$$

- Expected Loss** of Triplet Classifier f_w : Measured on the **full triplet set** \mathcal{E}

$$\mathcal{L}_{0, \mathcal{E}}(f_w) = \frac{1}{|\mathcal{E}|} \sum_{(h, r, t) \in \mathcal{E}} \mathbf{1}[f_w(h, r, t)[y_{hrt}] \leq f_w(h, r, t)[1 - y_{hrt}]]$$

Generalization Bounds for ReED: Proof Sketch



PAC-Bayesian Generalization Bounds for ReED

- The generalization bounds for ReED with the **TD decoder** and **SM decoder**

Theorem 4.4 & 4.5 For any $L \geq 0$, let $f_w: \mathcal{V} \times \mathcal{R} \times \mathcal{V} \rightarrow \mathbb{R}^2$ be a triplet classifier designed by the combination of the RAMP encoder with L -layers and the triplet classification decoder. Let k_r be the maximum of the infinity norms for all possible $s_r^{(l)}$ in the RAMP encoder. Then, for any $\delta, \gamma > 0$, with probability at least $1 - \delta$ over a training triplet set $\hat{\mathcal{E}}$, for any w , we have

$$\mathcal{L}_{0, \mathcal{E}}(f_w) \leq \mathcal{L}_{\gamma, \hat{\mathcal{E}}}(f_w) + \begin{cases} \mathcal{O} \left(\sqrt{\left(\frac{1}{|\hat{\mathcal{E}}|} - \frac{1}{|\mathcal{E}|} \right) \left[\frac{N_w L^2 \zeta_L^2 s^{2L} d \ln(N_w d)}{\gamma^2} + \ln \frac{\theta(|\hat{\mathcal{E}}|, |\mathcal{E}|)}{\delta} \right]} \right) & \text{(TD)} \\ \mathcal{O} \left(\sqrt{\left(\frac{1}{|\hat{\mathcal{E}}|} - \frac{1}{|\mathcal{E}|} \right) \left[\frac{N_w L^2 \eta_L^4 s^{4L} d \ln(N_w d)}{\gamma^2} + \ln \frac{\theta(|\hat{\mathcal{E}}|, |\mathcal{E}|)}{\delta} \right]} \right) & \text{(SM)} \end{cases}$$

where $\theta(|\hat{\mathcal{E}}|, |\mathcal{E}|) = 3 \sqrt{|\hat{\mathcal{E}}| \left(1 - \frac{|\hat{\mathcal{E}}|}{|\mathcal{E}|} \right) \ln |\hat{\mathcal{E}}|}$, $\zeta_L = 2\tau^L \|\mathbf{X}_{\text{ent}}\|_2 + 2\kappa \|\mathbf{X}_{\text{ent}}\|_2 \left(\sum_{i=0}^{L-1} \tau^i \right) + \|\mathbf{X}_{\text{rel}}\|_2$, $\eta_L = \tau^L \|\mathbf{X}_{\text{ent}}\|_2 + \kappa \|\mathbf{X}_{\text{rel}}\|_2 \left(\sum_{i=0}^{L-1} \tau^i \right)$, $\tau = C_\phi + \kappa$, $\kappa = C_\phi C_\rho C_\psi \sum_{r \in \mathcal{R}} k_r$, N_w is the total number of learnable matrices, d is the maximum dimension, and s is the maximum Frobenius norm of the learnable matrices

Generalization Bounds for ReED: a Simplified Form

- Leaving **model-dependent terms** and regarding the rest as a constant

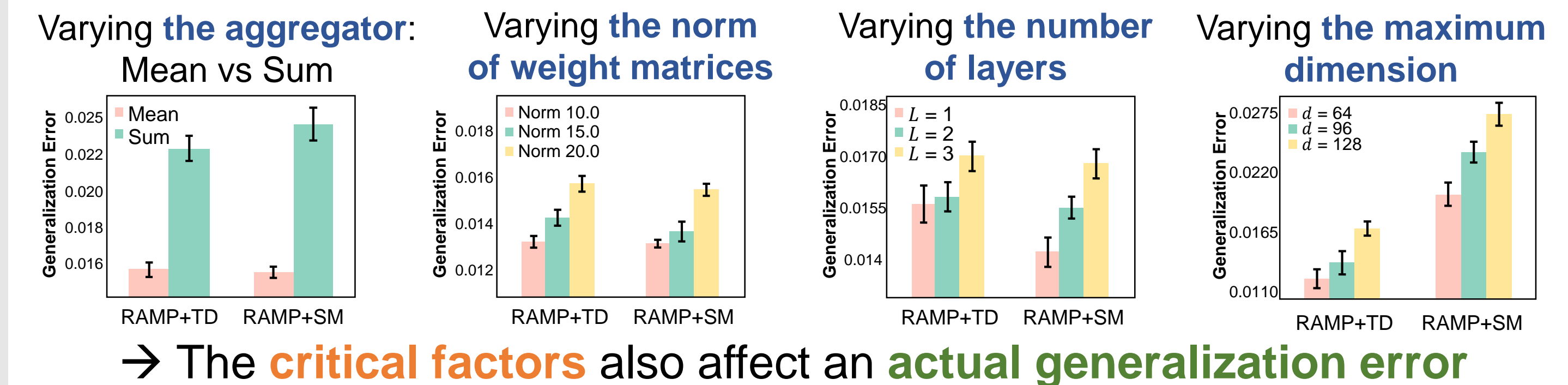
$$\mathcal{L}_{0, \mathcal{E}}(f_w) \leq \mathcal{L}_{\gamma, \hat{\mathcal{E}}}(f_w) + \begin{cases} \mathcal{O}(L(\sum_{r \in \mathcal{R}} k_r)^L s^L \sqrt{N_w \ln N_w}) & \text{(TD)} \\ \mathcal{O}(L(\sum_{r \in \mathcal{R}} k_r)^{2L} s^{2L} \sqrt{N_w \ln N_w}) & \text{(SM)} \end{cases}$$

- Practical implications** that can guide the desirable designs of KGRL

- k_r : **Maximum of the infinity norms** for all possible $s_r^{(l)}$
 - A **mean aggregator** can be a better option than a **sum aggregator**
- N_w : **Total number** of learnable matrices ($= \mathcal{O}(|\mathcal{R}|L)$)
 - Parameter-sharing** strategies & **basis/block decomposition** ideas
- s : **Maximum Frobenius norm** of the learnable matrices
 - Weight normalization** & **Normalization of entity representations**

Experimental Results

- Measure the generalization errors** on real-world knowledge graphs



Conclusion

- A novel **ReED framework** expressing at least 15 KGRL methods
- The **first PAC-Bayesian generalization bounds** for ReED with two different types of decoders: **TD decoder** and **SM decoder**
- Provide **theoretical grounds** for **commonly used tricks** in KGRL
- Empirically show the relationship between **the critical factors in the theoretical bounds** and **the actual generalization errors**